Naive Bayes Text Classification

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Outline

Basic Probability and Notation Bayes Law and Naive Bayes Classification Smoothing **Class Prior Probabilities** Naive Bayes Classification Summary

Crash Course in Basic Probability

Discrete Random Variable

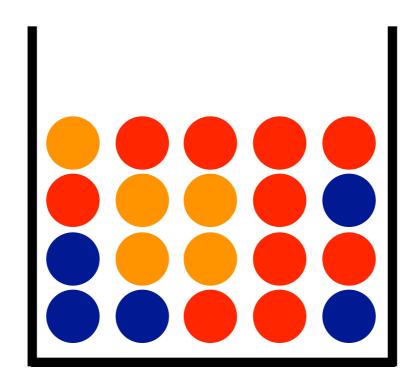
- A is a discrete random variable if:
 - A describes an event with a finite number of possible outcomes (discrete vs continuous)
 - A describes an event whose outcomes have some degree of uncertainty (random vs. pre-determined)

Discrete Random Variables Examples

- A = the outcome of a coin-flip
 - outcomes: heads, tails
- A = it will rain tomorrow
 - outcomes: rain, no rain
- A = you have the flu
 - outcomes: flu, no flu
- A = your final grade in this class
 - outcomes: F, L, P, H

Discrete Random Variables Examples

- A = the color of a ball pulled out from this bag
 - outcomes: **RED**, **BLUE**, **ORANGE**

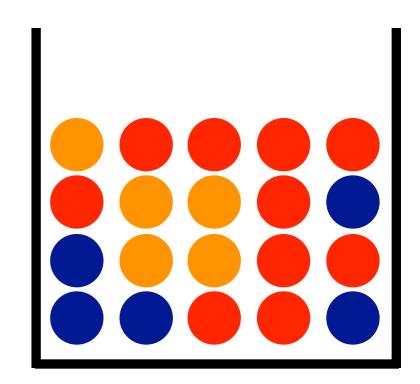


Probabilities

- Let P(A=X) denote the probability that the outcome of event A equals X
- For simplicity, we often express P(A=X) as P(X)
- Ex: P(RAIN), P(NO RAIN), P(FLU), P(NO FLU), ...

Probability Distribution

- A probability distribution gives the probability of each possible outcome of a random variable
- P(RED) = probability of pulling out a red ball
- P(BLUE) = probability of pulling out a blue ball
- P(ORANGE) = probability of pulling out an orange ball



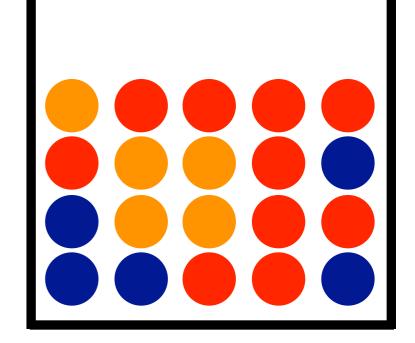
Probability Distribution

- For it to be a probability distribution, two conditions must be satisfied:
 - the probability assigned to each possible outcome must be between 0 and 1 (inclusive)
 - the <u>sum</u> of probabilities assigned to all outcomes must equal 1

 $0 \le P(RED) \le I$ $0 \le P(BLUE) \le I$ $0 \le P(ORANGE) \le I$ P(RED) + P(BLUE) + P(ORANGE) = I

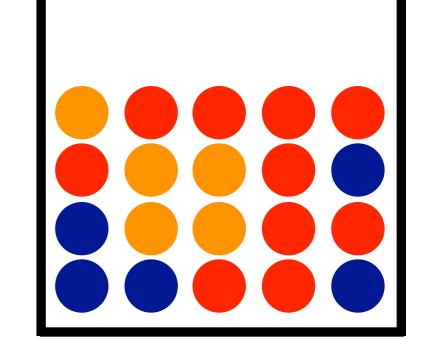
Probability Distribution Estimation

- Let's estimate these probabilities based on what we know about the contents of the bag
- **P(RED)** = ?
- **P(BLUE)** = ?
- **P(ORANGE)** = ?



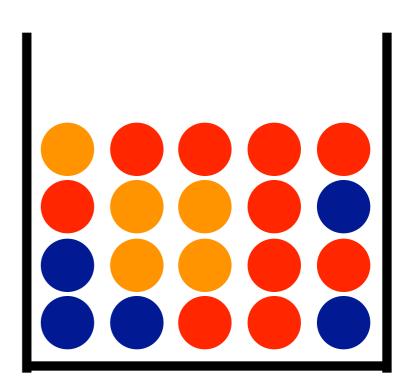
Probability Distribution estimation

- Let's estimate these probabilities based on what we know about the contents of the bag
- P(RED) = 10/20 = 0.5
- P(BLUE) = 5/20 = 0.25
- P(ORANGE) = 5/20 = 0.25
- P(RED) + P(BLUE) + P(ORANGE) = 1.0



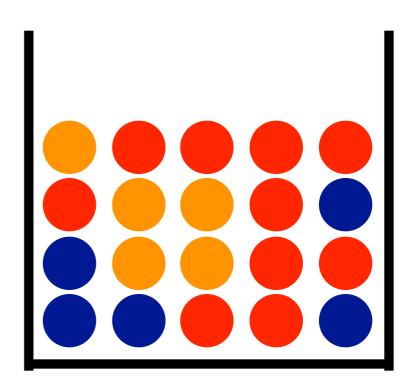
Probability Distribution assigning probabilities to outcomes

- Given a probability distribution, we can assign probabilities to different outcomes
- I reach into the bag and pull out an orange ball. What is the probability of that happening?
- I reach into the bag and pull out two balls: one red, one blue.
 What is the probability of that happening?
- What about three orange balls?



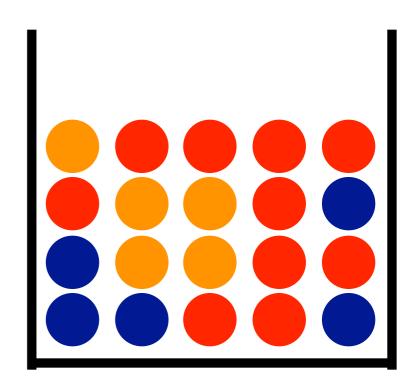
What can we do with a probability distribution?

- If we assume that each outcome is independent of previous outcomes, then the probability of a <u>sequence</u> of outcomes is calculated by <u>multiplying</u> the individual probabilities
- Note: we're assuming that when you take out a ball, you put it back in the bag before taking another



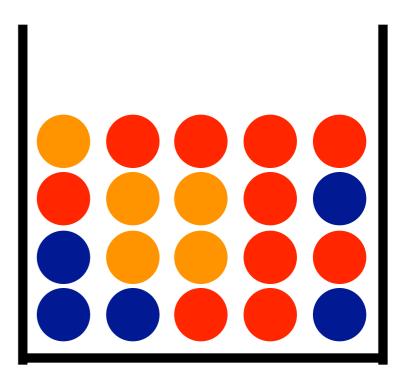
What can we do with a probability distribution?

- P() = ??



What can we do with a probability distribution?

- $P(\bigcirc) = 0.25$
- P(-) = 0.5
- $P(-) = 0.25 \times 0.25 \times 0.25$
- $P(-) = 0.25 \times 0.25 \times 0.25$
- $P(-) = 0.25 \times 0.50 \times 0.25$
- $P(\bigcirc \bigcirc \bigcirc \bigcirc) = 0.25 \times 0.50 \times 0.25 \times 0.50$

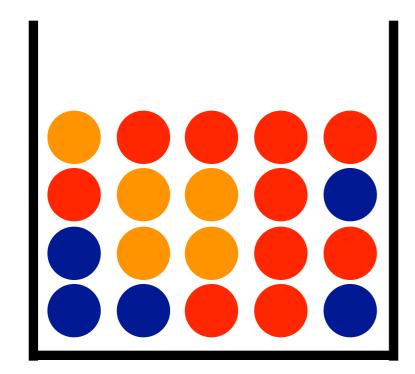


Conditional Probability

- P(A,B): the probability that event A <u>and</u> event B both occur
- P(A|B): the probability of event A occurring given prior knowledge that event B occurred

Conditional Probability

P(RED) = 0.50P(BLUE) = 0.25P(ORANGE) = 0.25

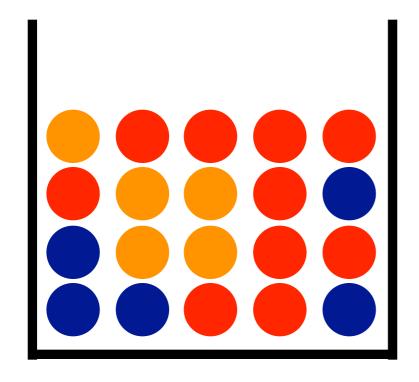


•
$$P(- | A) = ??$$

P(RED) = 0.50P(BLUE) = 0.00P(ORANGE) = 0.50B | B) = ??P(• **B**) = ?? P((•

Conditional Probability

P(RED) = 0.50P(BLUE) = 0.25P(ORANGE) = 0.25



• $P(\bigcirc | A) = 0.25$

• P(-|A) = 0.50

P(RED) = 0.50P(BLUE) = 0.00P(ORANGE) = 0.50B **P(** $| \mathbf{B} | = 0.00$ • • P($| \mathbf{B} | = 0.25$

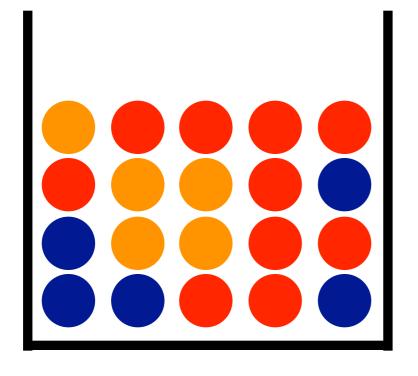
P((

 $| B) = 0.00_{18}$

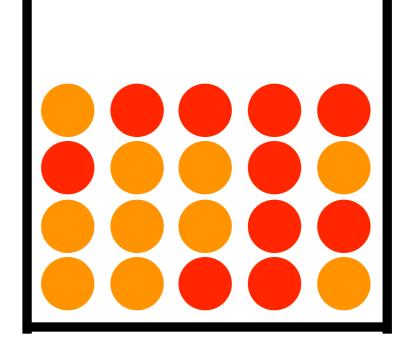
Chain Rule

- $P(A, B) = P(A|B) \times P(B)$
- Example:
 - probability that it will rain today (B) <u>and</u> tomorrow (A)
 - probability that it will rain today (B)
 - probability that it will rain tomorrow (A) given that it will rain today (B)

- $P(A, B) = P(A|B) \times P(B) = P(A) \times P(B)$
- Example:
 - probability that it will rain today (B) <u>and</u> tomorrow (A)
 - probability that it will rain today (**B**)
 - probability that it will rain tomorrow (A) given that it will rain today (B)
 - probability that it will rain tomorrow (A)

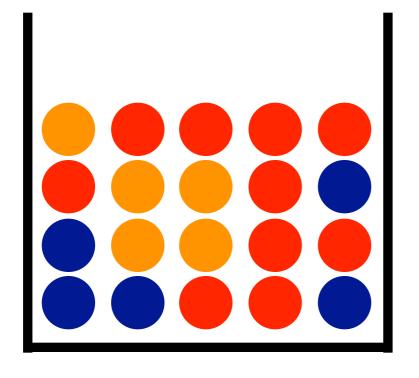


A

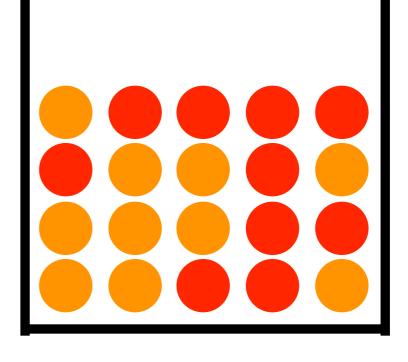


B

 $P(\bigcirc | A) ?= P(\bigcirc)$

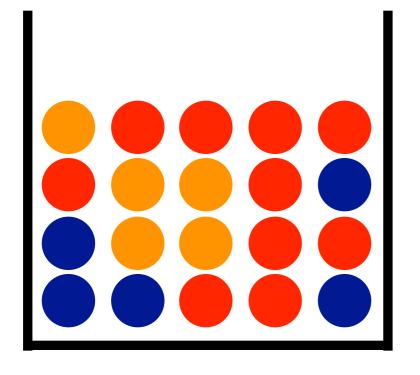


A

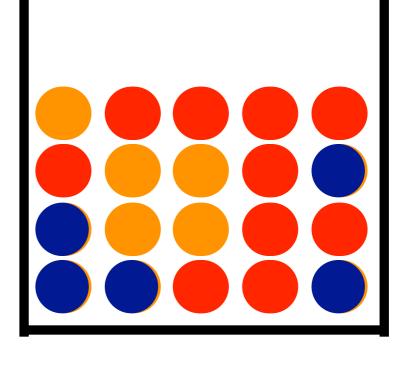


B

 $P(\bigcirc | A) > P(\bigcirc)$

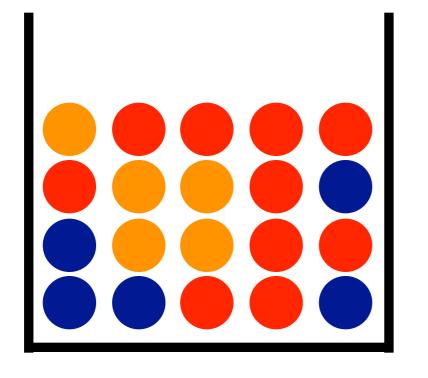


A

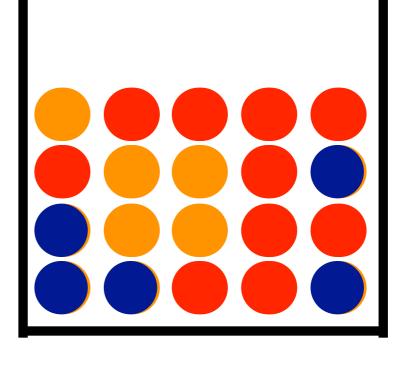


В

 $\mathsf{P}(\bigcirc | \mathsf{A}) ?= \mathsf{P}(\bigcirc)$



A



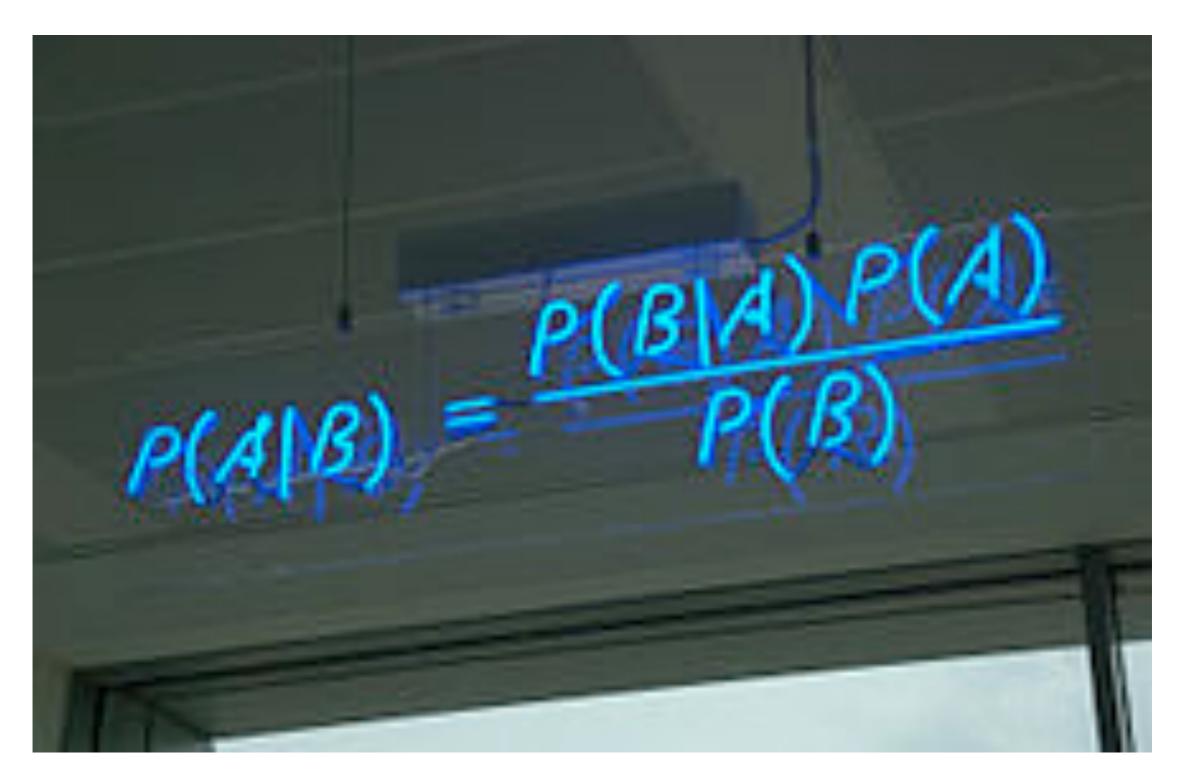
B

$\mathsf{P}(\bigcirc | \mathsf{A}) = \mathsf{P}(\bigcirc)$

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Basic Probability and Notation Bayes Law and Naive Bayes Classification Smoothing **Class Prior Probabilities** Naive Bayes Classification Summary

Bayes' Law



Bayes' Law

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

Bayes' Law

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

How do we get this?

Derivation of Bayes' Law

P(A,B) = P(A,B)	Always true!
$P(A B) \times P(B) = P(B A) \times (B)$	Chain Rule!
$P(A B) = \frac{P(B A) \times P(A)}{P(B)}$	Divide both sides by P(B)!

Bayes Rule
$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

Confidence of POS prediction given instance D

 $P(POS|D) = \frac{P(D|POS) \times P(POS)}{P(D)}$

Confidence of NEG prediction given instance D

$$P(NEG|D) = \frac{P(D|NEG) \times P(NEG)}{P(D)}$$

• Given instance D, predict positive (POS) if:

$P(POS|D) \ge P(NEG|D)$

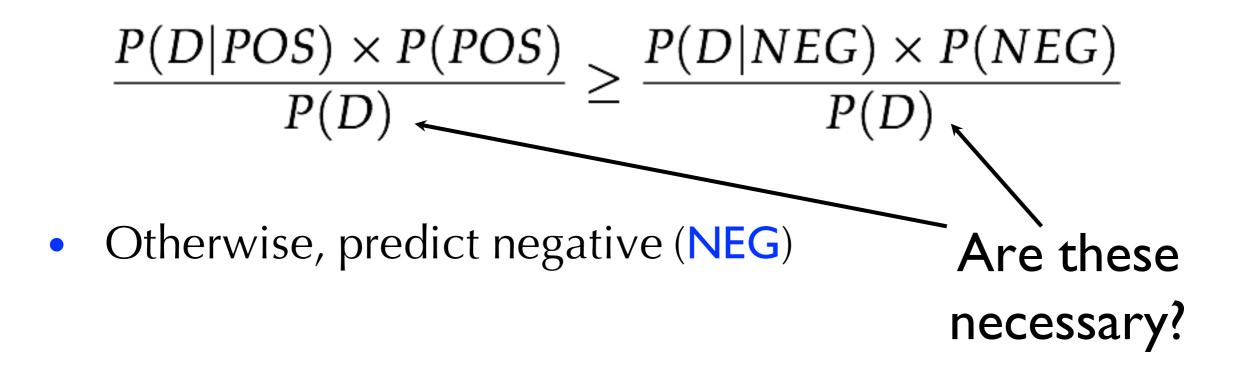
• Otherwise, predict negative (**NEG**)

• Given instance D, predict positive (POS) if:

$$\frac{P(D|POS) \times P(POS)}{P(D)} \ge \frac{P(D|NEG) \times P(NEG)}{P(D)}$$

• Otherwise, predict negative (**NEG**)

• Given instance D, predict positive (POS) if:

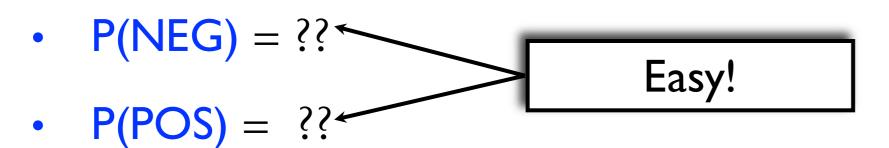


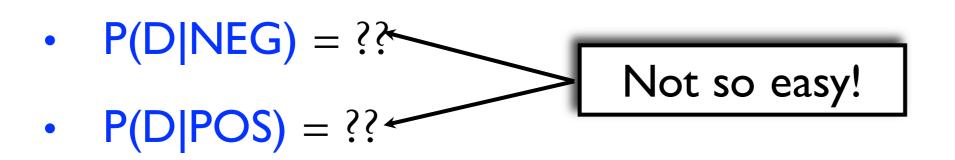
• Given instance D, predict positive (POS) if:

$P(D|POS) \times P(POS) \ge P(D|NEG) \times P(NEG)$

• Otherwise, predict negative (**NEG**)

• Our next goal is to estimate these parameters from the training data!

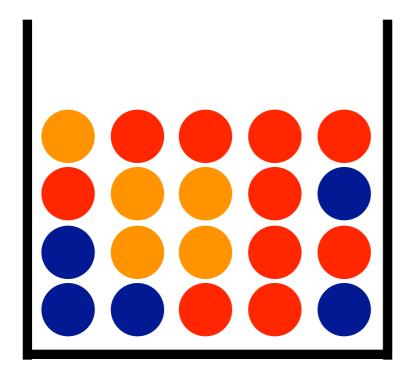




- Our next goal is to estimate these parameters from the training data!
- **P(NEG)** = % of training set documents that are **NEG**
- **P(POS)** = % of training set documents that are **POS**
- **P(D|NEG)** = ??
- **P(D|POS)** = ??

Remember Conditional Probability?

P(RED) = 0.50P(BLUE) = 0.25P(ORANGE) = 0.25



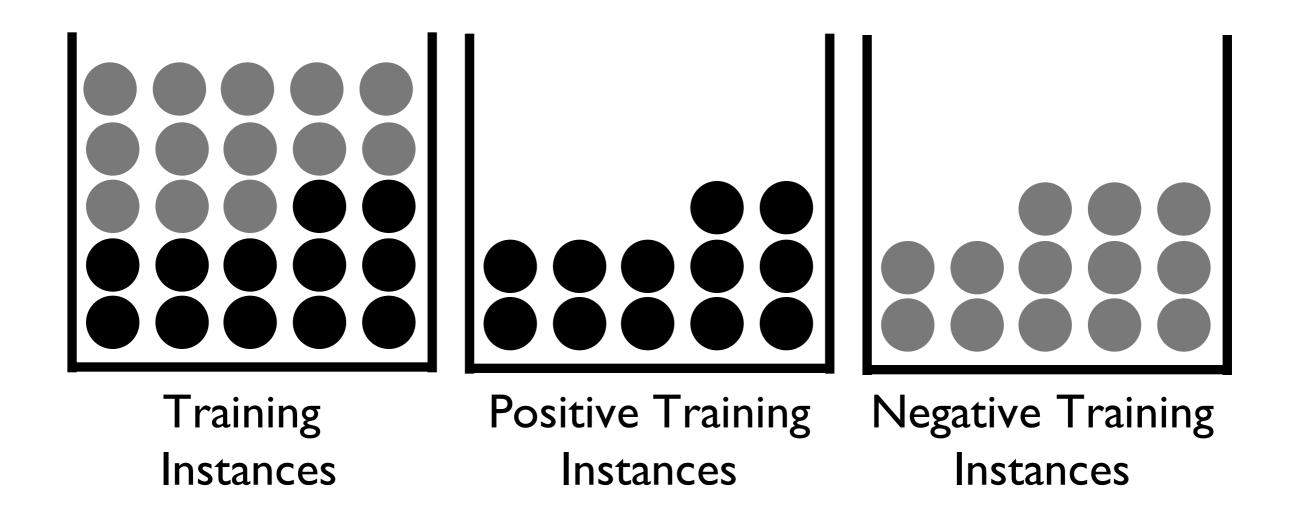
- $P(\bullet | A) = 0.25$
- P(-|A) = 0.50
- P(| A) = 0.25

P(RED) = 0.50P(BLUE) = 0.00P(ORANGE) = 0.50

• $P(\bigcirc | B) = 0.00$

•
$$P(-|B) = 0.50$$

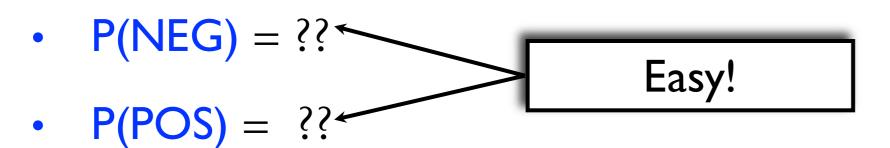
• P(-|B) = 0.50

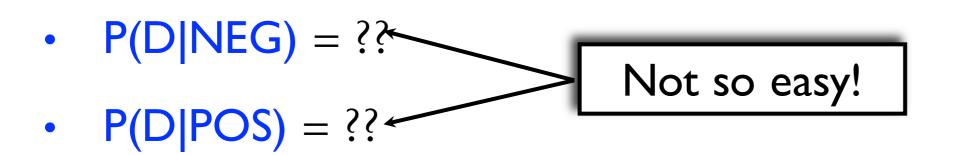


P(D|POS) = ?? P(D|NEG) = ??

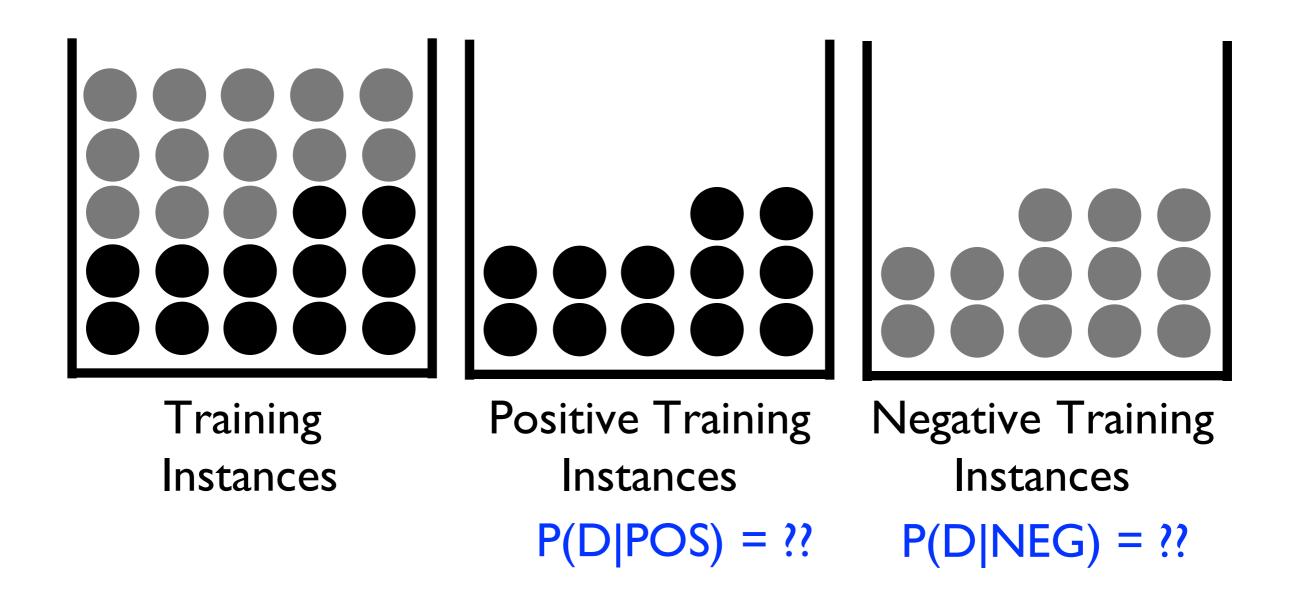
w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8		w_n	sentiment
1	0	I	0	I	0	0	I	•••	0	positive
0	I	0	I	I	0	I	I		0	positive
0	I	0	I	I	0	I	0		0	positive
0	0	I	0	I	I	0	I	••••	I	positive
	•	•	•	•	•	•	•	•••	•	
Ι	Ι	0	I	I	0	0	I		I	positive

• Our next goal is to estimate these parameters from the training data!

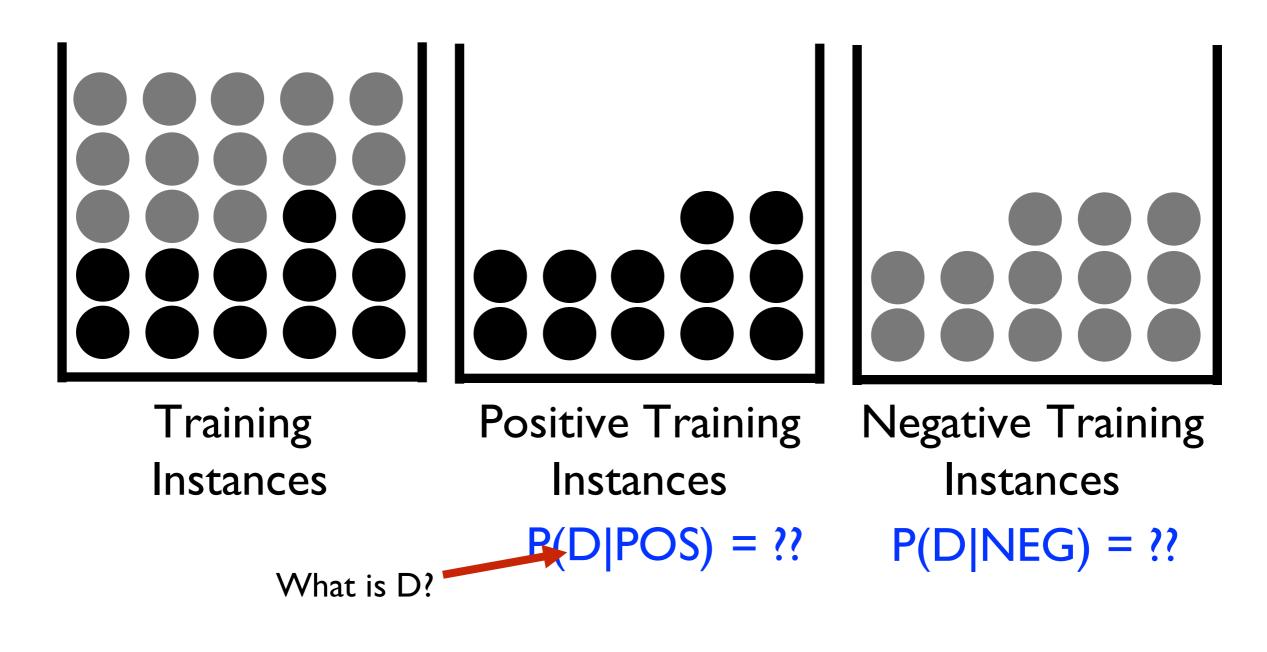




• We have a problem! What is it?



• We have a problem! What is it?



What is the Document representation?

- Lets say that our feature space is limited by the following words: w_1, w_2, and w_3.
- Total possible features are:
- w_1, w_2, w_3
- w_1 w_2, w_1 w_3, w_2 w_3
- w_1 w_2 w_3, w_1 w_2 w_4
- Total = 8
- If say our feature space was: w_1, w_2, w_3, and w_4. Then total feature possible combinations are: ?

Feature combinations

- Lets say that our feature space is limited by the following words: w_1, w_2, and w_3.
- Total possible features are:
- w_1, w_2, w_3
- w_1 w_2, w_1 w_3, w_2 w_3
- w_1 w_2 w_3
- Total = 8 => 7 (above combinations) + 1 (no combination)
- If say our feature space was: w_1, w_2, w_3, and w_4. Then total feature possible combinations are: 2⁴

- We have a problem! What is it?
- Assuming n binary features, the number of possible combinations is 2ⁿ
- $2^{1000} = 1.071509e+301$
- And in order to estimate the probability of each combination, we would require multiple occurrences of each combination in the training data!
- We could never have enough training data to reliably estimate P(D|NEG) or P(D|POS)!

- Assumption: given a particular class value (i.e, POS or NEG), the value of a particular feature is independent of the value of other features
- In other words, the value of a particular feature is only dependent on the class value

w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8		w_n	sentiment
Ι	0	Ι	0	Ι	0	0	Ι	••••	0	positive
0	I	0	Ι	Ι	0	I	I		0	positive
0	Ι	0	Ι	Ι	0	Ι	0		0	positive
0	0	I	0	I	I	0	I		I	positive
•	•	•	•	•	•	••••	•		•	
Ι	Ι	0	Ι	Ι	0	0	Ι	•••	Ι	positive

Example of document representation

- Assume the feature space to be the following words: hello, world, bad, movie.
- Review 1: "this is a bad movie!"
- Review 2: "hello world is a movie?"
- What is the bag-of-words document representation for review 1 and review 2?
- Review 1?
- Review 2?

Example of document representation

- Assume the feature space to be the following words: hello, world, bad, movie.
- Review 1: "this is a bad movie!"
- Review 2: "hello world is a movie?"
- What is the bag-of-words document representation for review 1 and review 2?
- Review 1: 0011
- Review 2: 1101

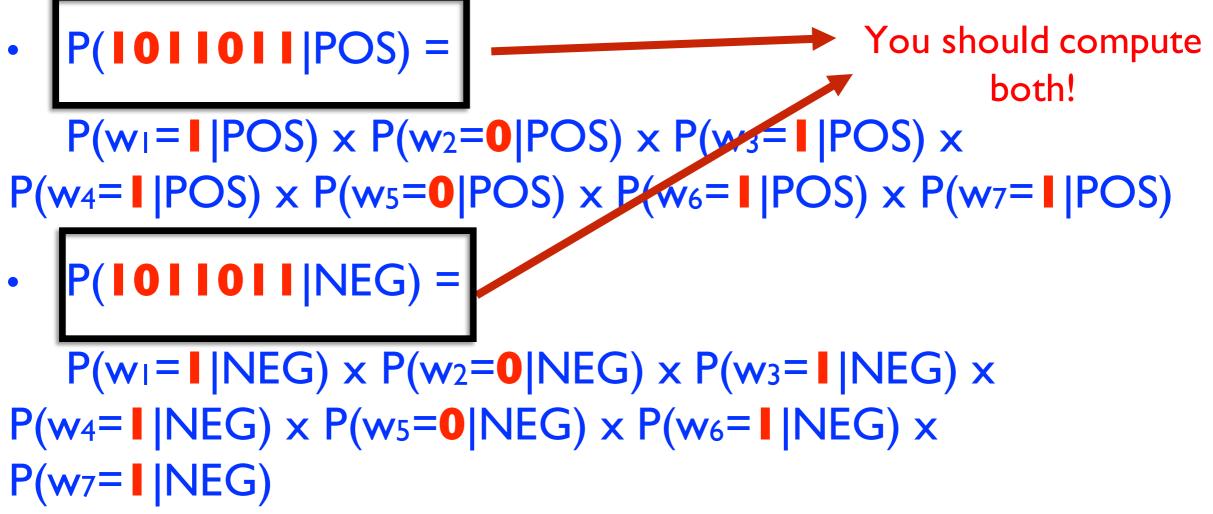
- Assumption: given a particular class value (i.e, POS or NEG), the value of a particular feature is independent of the value of other features
- Example: we have <u>seven</u> features and **D** = **IOIIOII**
- P(|0||0||POS) =

 $P(w_1=|POS) \times P(w_2=0|POS) \times P(w_3=|POS) \times P(w_4=|POS) \times P(w_5=0|POS) \times P(w_6=|POS) \times P(w_7=|POS)$

• P(|0||0||NEG) =

 $P(w_1=||NEG) \times P(w_2=0|NEG) \times P(w_3=||NEG) \times P(w_4=||NEG) \times P(w_5=0|NEG) \times P(w_6=||NEG) \times P(w_7=||NEG))$

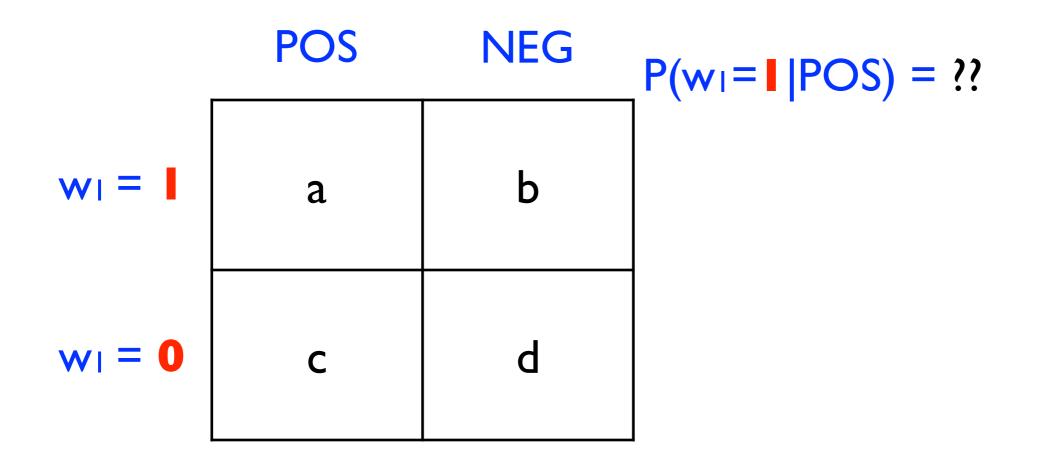
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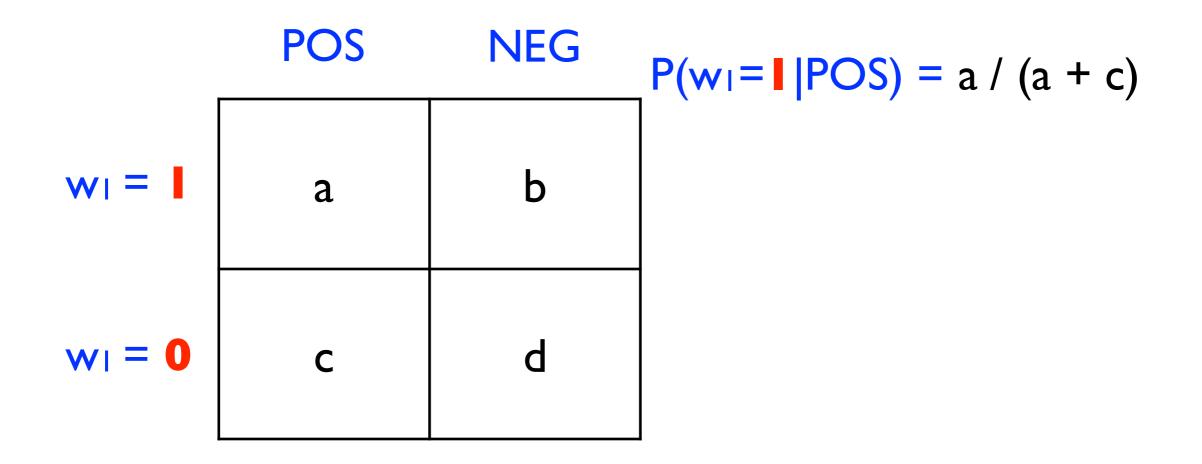
• Question: How do we estimate P(w = | POS) ?

w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8		w_n	sentiment
I	0	I	0	I	0	0	I	•••	0	positive
0	I	0	I	I	0	I	I	•••	0	negative
0	I	0	I	I	0	I	0	•••	0	negative
0	0	I	0	I	I	0	I		I	positive
	:	•	•	•	•	•			•	•
Ι	I	0	I	Ι	0	0	Ι	•••	Ι	negative

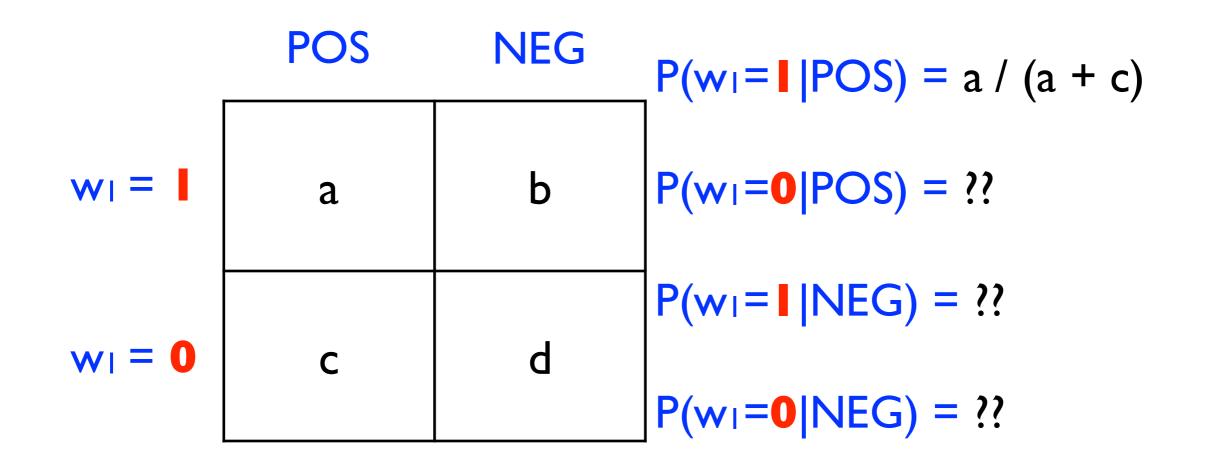
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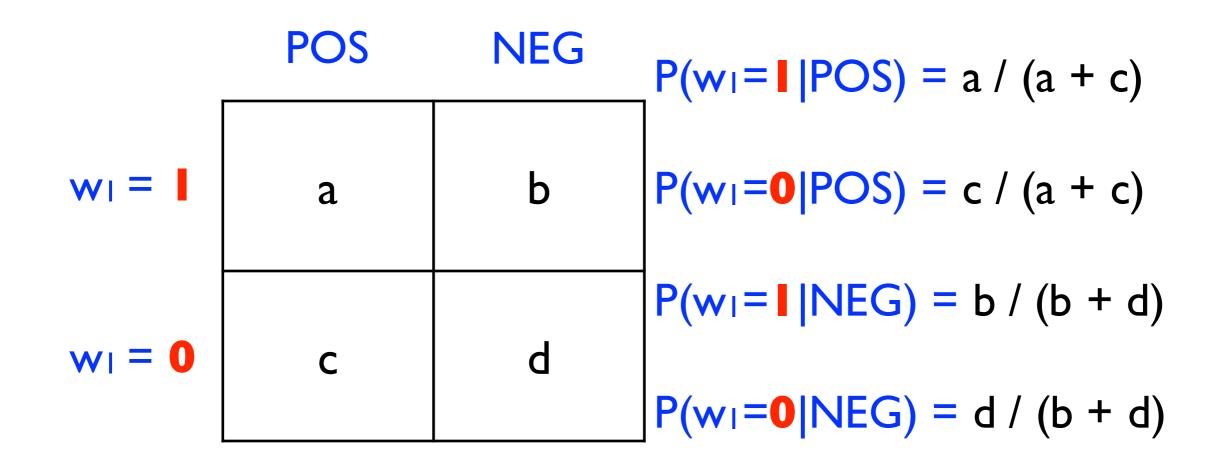
• Question: How do we estimate P(w = | POS) ?



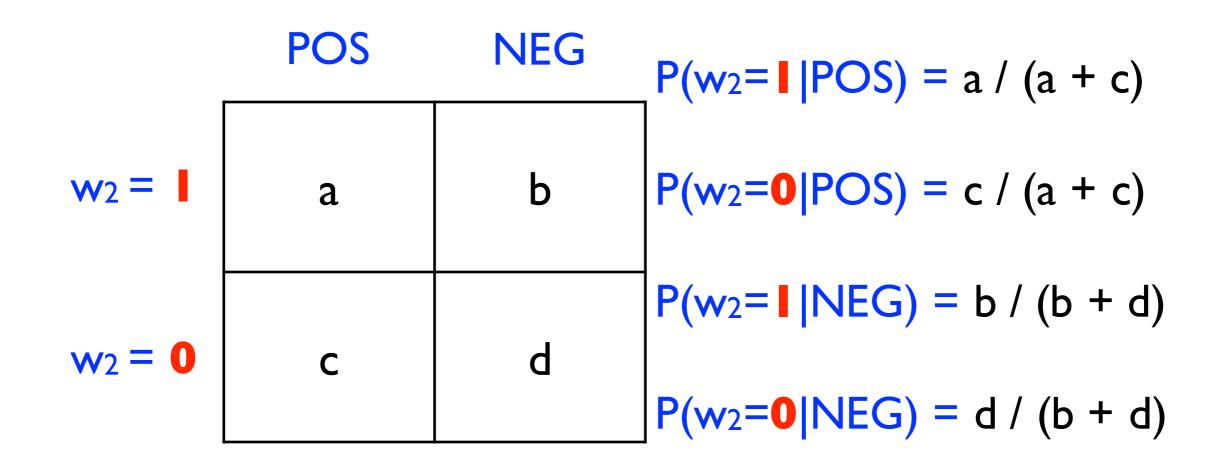
• Question: How do we estimate P(w1=1/0|POS/NEG)?



• Question: How do we estimate P(w1=1/0|POS/NEG)?



• Question: How do we estimate P(w₂=1/0|POS/NEG)?



 The value of a, b, c, and d would be different for different features w1, w2, w3, w4, w5,, wn

• Given instance **D**, predict positive (**POS**) if:

$P(D|POS) \times P(POS) \ge P(D|NEG) \times P(NEG)$

• Given instance **D**, predict positive (**POS**) if:

$$P(POS) \times \prod_{i=1}^{n} P(w_i = D_i | POS) \ge P(NEG) \times \prod_{i=1}^{n} P(w_i = D_i | NEG)$$

Given instance D = [0][0][, predict positive (POS) if:
 P(w1=[POS) x P(w2=0|POS) x P(w3=1|POS) x P(w4=1|POS) x
 P(w5=0|POS) x P(w6=1|POS) x P(w7=1|POS) x P(POS)

\geq

 $P(w_1 = | | NEG) \times P(w_2 = 0 | NEG) \times P(w_3 = | | NEG) \times P(w_4 = | | NEG) \times P(w_5 = 0 | NEG) \times P(w_6 = | | NEG) \times P(w_7 = | | NEG) \times P(NEG) \times P(NEG)$

• We still have a problem! What is it?

• Given instance D = |0||0||, predict positive (POS) if: $P(w_1=|POS) \times P(w_2=0|POS) \times P(w_3=|POS) \times P(w_4=|POS) \times P(w_5=0|POS) \times P(w_6=|POS) \times P(w_7=|POS) \times P(POS)$

 $P(w_1 = | | NEG) \times P(w_2 = 0 | NEG) \times P(w_3 = | | NEG) \times P(w_4 = | | NEG) \times P(w_5 = 0 | NEG) \times P(w_6 = | | NEG) \times P(w_7 = | | NEG) \times P(NEG) \times P(NEG)$

Otherwise, predict negative (NEG)

What if this never happens in the training data?

Smoothing Probability Estimates

- When estimating probabilities, we tend to ...
 - Over-estimate the probability of observed outcomes
 - Under-estimate the probability of unobserved outcomes
- The goal of smoothing is to ...
 - Decrease the probability of observed outcomes
 - Increase the probability of unobserved outcomes
- It's usually a good idea
- You probably already know this concept!

Smoothing Probability Estimates

- YOU: Are there mountain lions around here?
- YOUR FRIEND: Nope.
- YOU: How can you be so sure?
- YOUR FRIEND: Because I've been hiking here five times before and have never seen one.
- YOU: ????

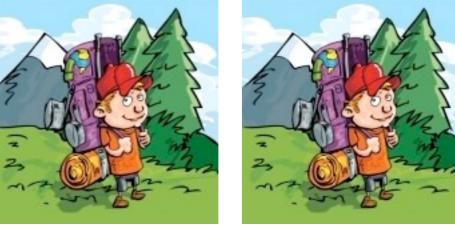




Smoothing Probability Estimates

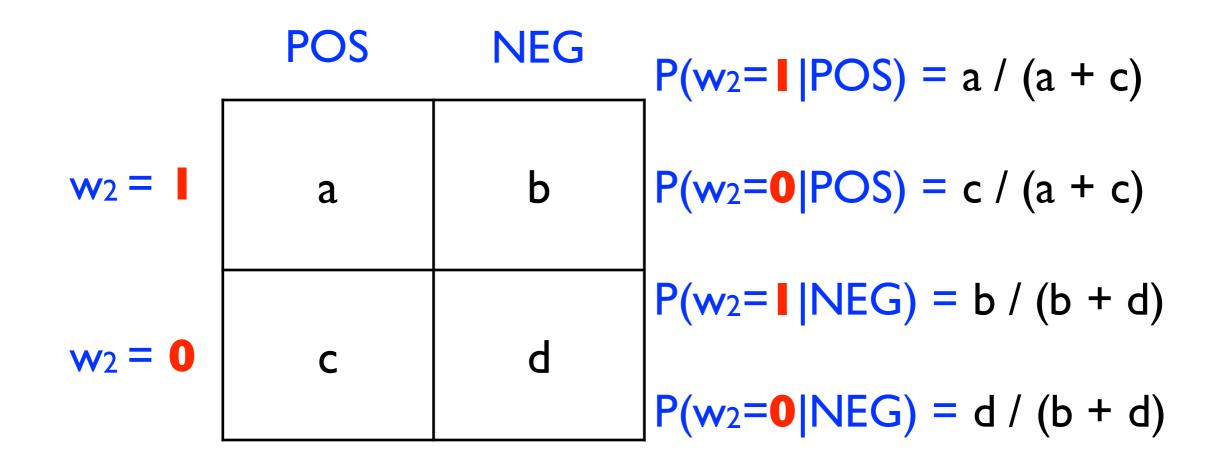
- YOU: Are there mountain lions around here?
- YOUR FRIEND: Nope.
- YOU: How can you be so sure?
- YOUR FRIEND: Because I've been hiking here five times before and have never seen one.
- MOUNTAIN LION: You should have learned about smoothing by taking INLS 613. Yum!





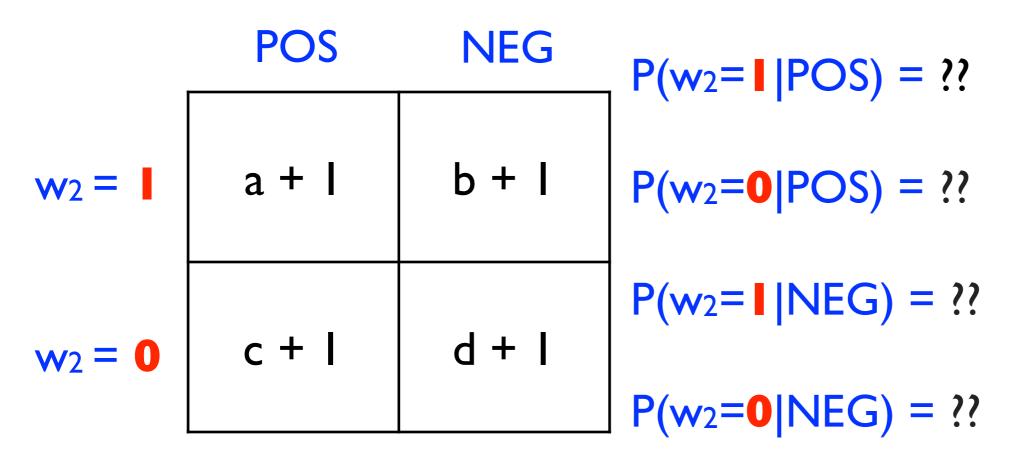
Add-One Smoothing

• Question: How do we estimate P(w₂=1/0|POS/NEG)?



Add-One Smoothing

• Question: How do we estimate P(w₂=1/0|POS/NEG)?



Add-One Smoothing

• Question: How do we estimate P(w₂=1/0|POS/NEG)?

	POS	NEG	$- P(w_2 = P \cap S) = (a + 1) / (a + c + 2)$
w ₂ =	a + 1	b + 1	$P(w_2=1 POS) = (a + 1) / (a + c + 2)$ $P(w_2=0 POS) = (c + 1) / (a + c + 2)$
w ₂ = 0	c +	d + 1	$P(w_2= NEG) = (b + 1) / (b + d + 2)$
			$P(w_2=0 NEG) = (d + I) / (b + d + 2)$

• Given instance **D**, predict positive (**POS**) if:

$$P(POS) \times \prod_{i=1}^{n} P(w_i = D_i | POS) \ge P(NEG) \times \prod_{i=1}^{n} P(w_i = D_i | NEG)$$

Naive Bayes Classification

- Naive Bayes Classifiers are simple, effective, robust, and very popular
- Assumes that feature values are conditionally independent given the target class value
- This assumption does not hold in natural language
- Even so, NB classifiers are very powerful
- Smoothing is necessary in order to avoid zero probabilities