#### Naive Bayes Text Classification

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## Outline

**Basic Probability and Notation Bayes Law and Naive Bayes Classification** Smoothing **Class Prior Probabilities** Naive Bayes Classification Summary

## Crash Course in Basic Probability

## Discrete Random Variable

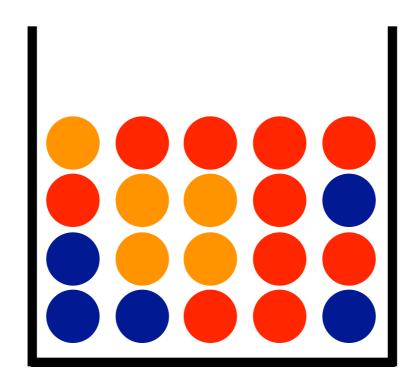
- A is a discrete random variable if:
  - A describes an event with a finite number of possible outcomes (discrete vs continuous)
  - A describes and event whose outcomes have some degree of uncertainty (random vs. pre-determined)

#### Discrete Random Variables Examples

- A = the outcome of a coin-flip
  - outcomes: heads, tails
- A = it will rain tomorrow
  - outcomes: rain, no rain
- A = you have the flu
  - outcomes: flu, no flu
- A = your final grade in this class
  - outcomes: F, L, P, H

#### Discrete Random Variables Examples

- A = the color of a ball pulled out from this bag
  - outcomes: **RED**, **BLUE**, **ORANGE**

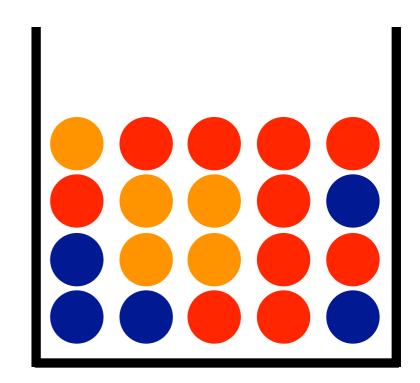


## Probabilities

- Let P(A=X) denote the probability that the outcome of event A equals X
- For simplicity, we often express P(A=X) as P(X)
- Ex: P(RAIN), P(NO RAIN), P(FLU), P(NO FLU), ...

# **Probability Distribution**

- A probability distribution gives the probability of each possible outcome of a random variable
- P(RED) = probability of pulling out a red ball
- P(BLUE) = probability of pulling out a blue ball
- P(ORANGE) = probability of pulling out an orange ball



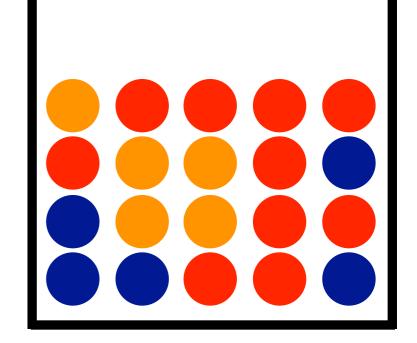
# **Probability Distribution**

- For it to be a probability distribution, two conditions must be satisfied:
  - the probability assigned to each possible outcome must be between 0 and 1 (inclusive)
  - the <u>sum</u> of probabilities assigned to all outcomes must equal 1

 $0 \le P(RED) \le I$  $0 \le P(BLUE) \le I$  $0 \le P(ORANGE) \le I$ P(RED) + P(BLUE) + P(ORANGE) = I

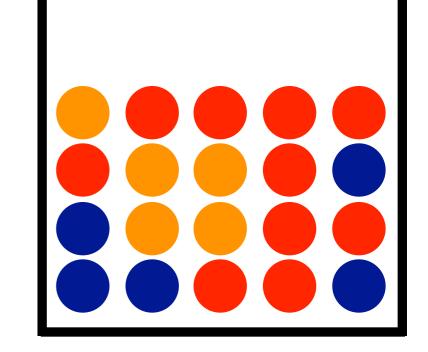
### Probability Distribution Estimation

- Let's estimate these probabilities based on what we know about the contents of the bag
- **P(RED)** = ?
- **P(BLUE)** = ?
- **P(ORANGE)** = ?



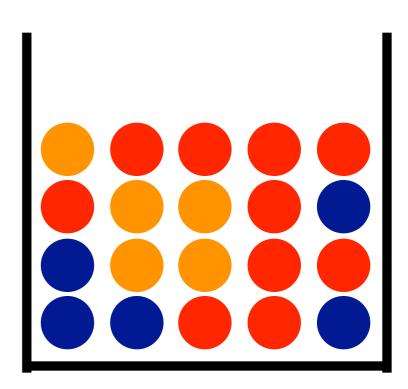
#### Probability Distribution estimation

- Let's estimate these probabilities based on what we know about the contents of the bag
- P(RED) = 10/20 = 0.5
- P(BLUE) = 5/20 = 0.25
- P(ORANGE) = 5/20 = 0.25
- P(RED) + P(BLUE) + P(ORANGE) = 1.0



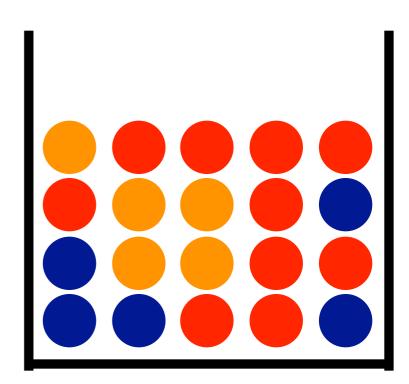
## Probability Distribution assigning probabilities to outcomes

- Given a probability distribution, we can assign probabilities to different outcomes
- I reach into the bag and pull out an orange ball. What is the probability of that happening?
- I reach into the bag and pull out two balls: one red, one blue.
   What is the probability of that happening?
- What about three orange balls?



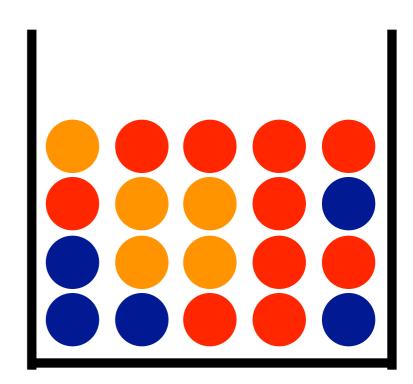
# What can we do with a probability distribution?

- If we assume that each outcome is independent of previous outcomes, then the probability of a <u>sequence</u> of outcomes is calculated by <u>multiplying</u> the individual probabilities
- Note: we're assuming that when you take out a ball, you put it back in the bag before taking another



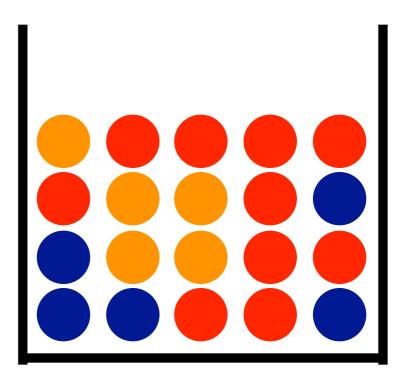
# What can we do with a probability distribution?

- P( ) = ??



# What can we do with a probability distribution?

- $P(\bigcirc) = 0.25$
- P(-) = 0.5
- $P(-) = 0.25 \times 0.25 \times 0.25$
- $P(-) = 0.25 \times 0.25 \times 0.25$
- $P(-) = 0.25 \times 0.50 \times 0.25$
- $P(\bigcirc \bigcirc \bigcirc \bigcirc) = 0.25 \times 0.50 \times 0.25 \times 0.50$

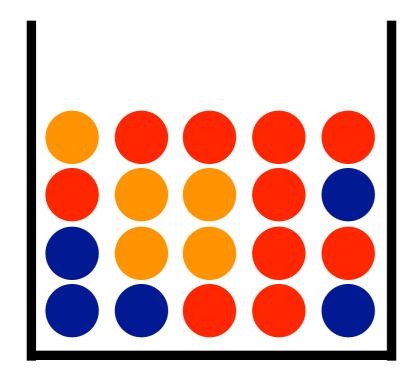


# **Conditional Probability**

- P(A,B): the probability that event A <u>and</u> event B both occur
- P(A|B): the probability of event A occurring given prior knowledge that event B occurred

## **Conditional Probability**

P(RED) = 0.50P(BLUE) = 0.25P(ORANGE) = 0.25



•  $P(\bigcirc | A) = ??$ 

P(RED) = 0.50P(BLUE) = 0.00P(ORANGE) = 0.50B **B**) = ?? P( • P( ( | B) = ??•

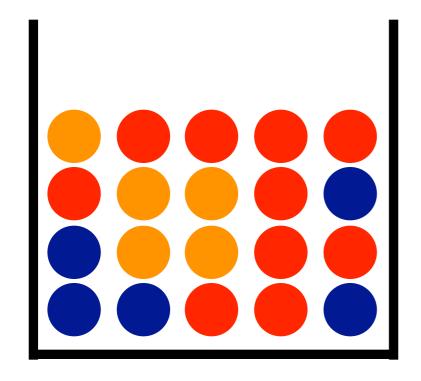
P( |

•

| B) = ??

## **Conditional Probability**

P(RED) = 0.50P(BLUE) = 0.25P(ORANGE) = 0.25



•  $P(\bigcirc | A) = 0.25$ 

- P(-|A) = 0.50

P(RED) = 0.50P(BLUE) = 0.00P(ORANGE) = 0.50B **P(**  $| \mathbf{B} | = 0.00$ • • P(  $| \mathbf{B} | = 0.25$ 

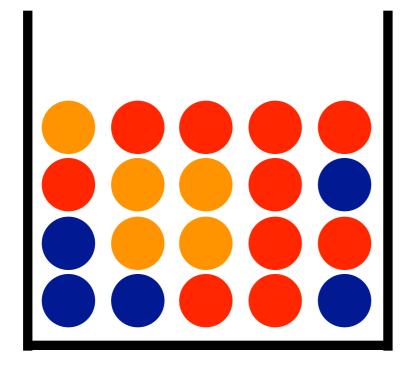
P( (

| B) = 0.00

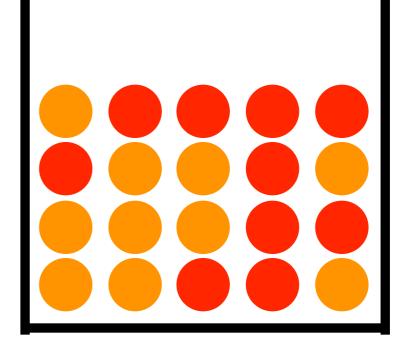
# Chain Rule

- $P(A, B) = P(A|B) \times P(B)$
- Example:
  - probability that it will rain today (B) <u>and</u> tomorrow (A)
  - probability that it will rain today (B)
  - probability that it will rain tomorrow (A) given that it will rain today (B)

- $P(A, B) = P(A|B) \times P(B) = P(A) \times P(B)$
- Example:
  - probability that it will rain today (B) <u>and</u> tomorrow (A)
  - probability that it will rain today (B)
  - probability that it will rain tomorrow (A) given that it will rain today (B)
  - probability that it will rain tomorrow (A)

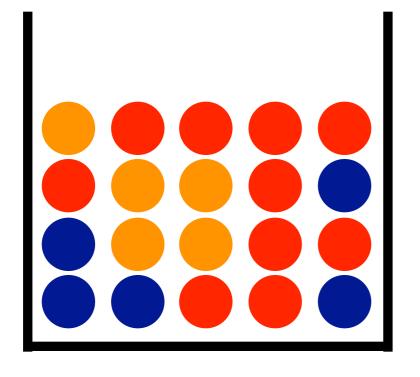


A

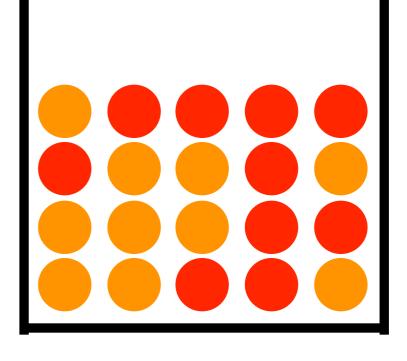


B

 $\mathsf{P}(\bigcirc | \mathsf{A}) ?= \mathsf{P}(\bigcirc)$ 

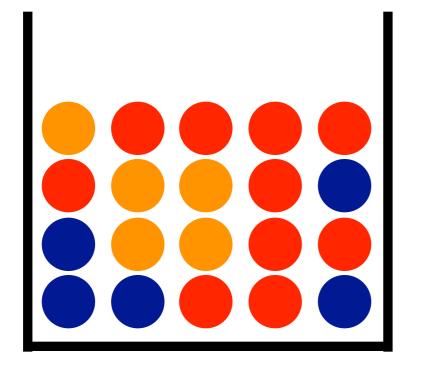


A

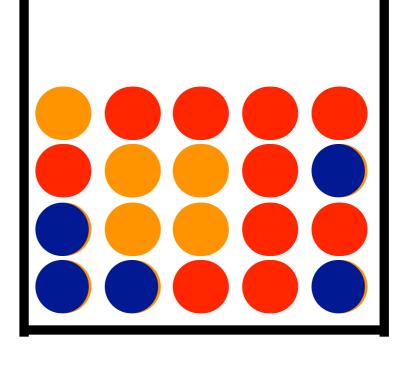


B

 $P(\bigcirc | A) > P(\bigcirc)$ 

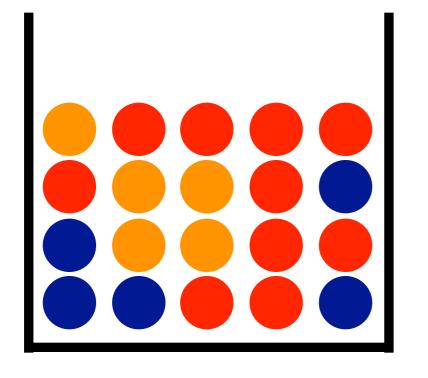


A

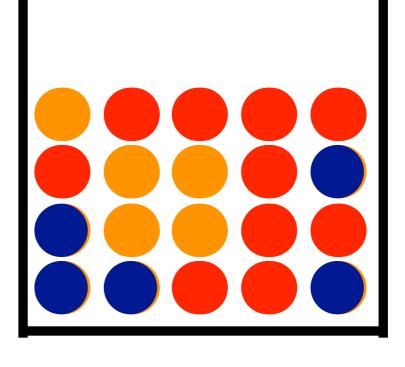


В

 $\mathsf{P}(\bigcirc | \mathsf{A}) ?= \mathsf{P}(\bigcirc)$ 



A



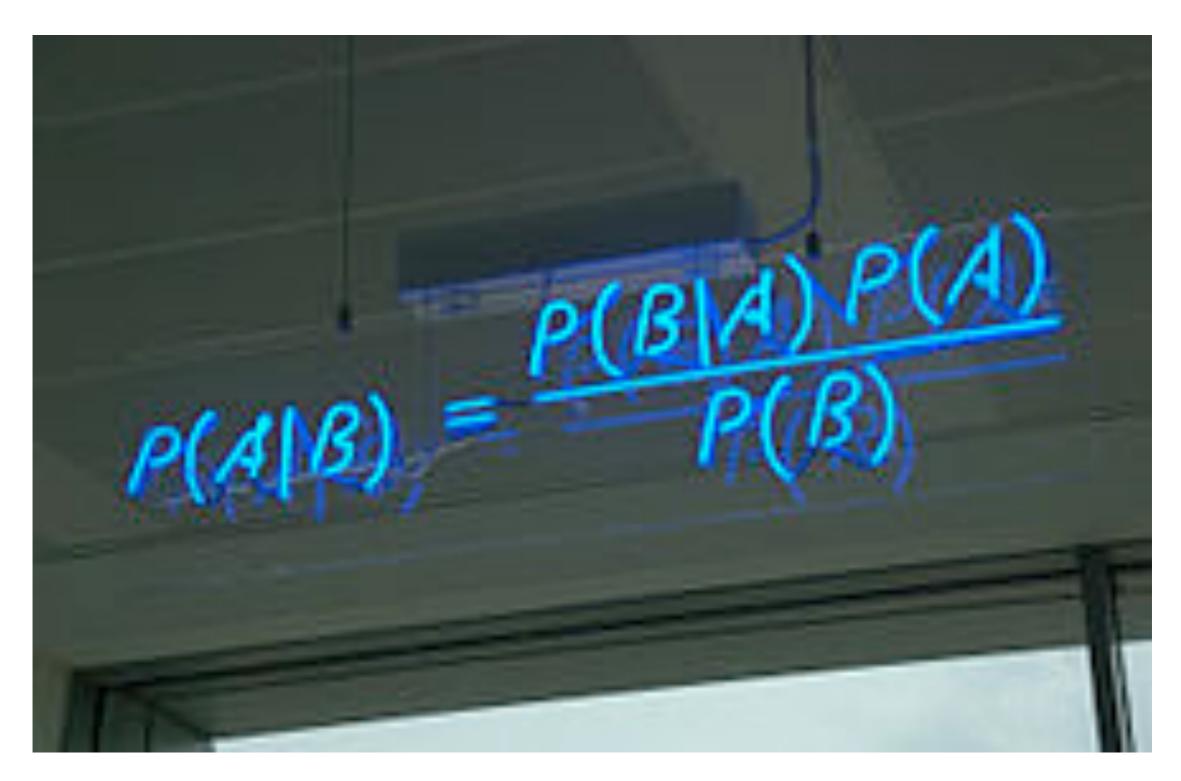
B

## $\mathsf{P}(\bigcirc | \mathsf{A}) = \mathsf{P}(\bigcirc)$

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# Bayes' Law



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$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

### Bayes' Law

$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

How do we get this?

## Derivation of Bayes' Law

P(A,B) = P(A,B)	Always true!
$P(A B) \times P(B) = P(B A) \times (B)$	Chain Rule!
$P(A B) = \frac{P(B A) \times P(A)}{P(B)}$	Divide both sides by P(B)!

Bayes Rule 
$$P(A|B) = \frac{P(B|A) \times P(A)}{P(B)}$$

Confidence of POS prediction given instance D

Confidence of **NEG** prediction given instance D

$$P(NEG|D) = \frac{P(D|NEG) \times P(NEG)}{P(D)}$$

$$P(POS|D) = \frac{P(D|POS) \times P(POS)}{P(D)}$$

• Given instance D, predict positive (POS) if:

### $P(POS|D) \ge P(NEG|D)$

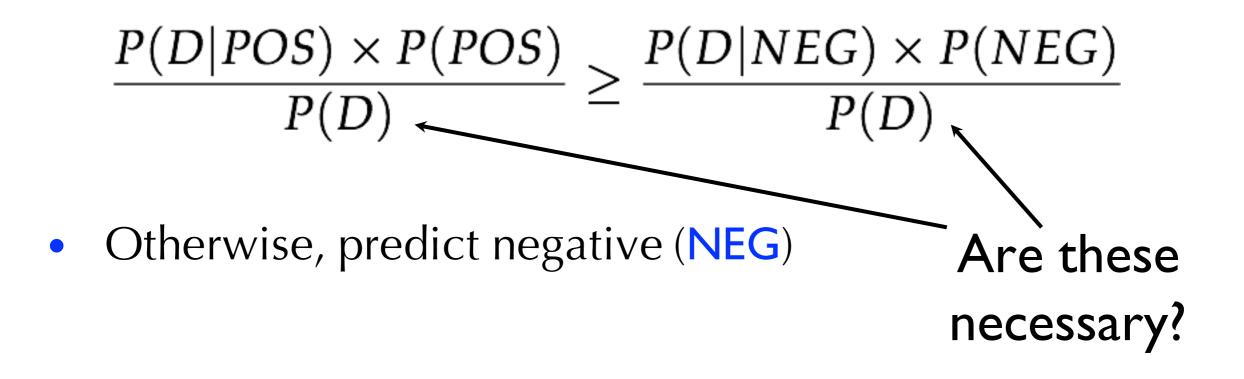
• Otherwise, predict negative (**NEG**)

• Given instance D, predict positive (POS) if:

$$\frac{P(D|POS) \times P(POS)}{P(D)} \ge \frac{P(D|NEG) \times P(NEG)}{P(D)}$$

• Otherwise, predict negative (**NEG**)

• Given instance D, predict positive (POS) if:

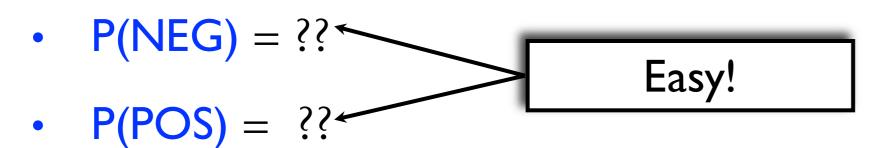


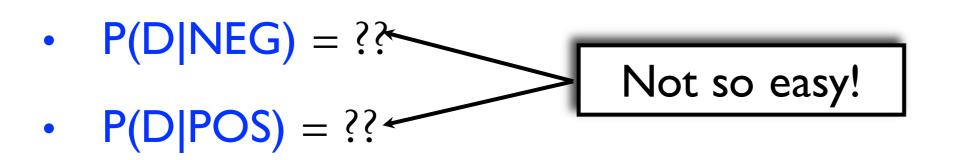
• Given instance D, predict positive (POS) if:

#### $P(D|POS) \times P(POS) \ge P(D|NEG) \times P(NEG)$

• Otherwise, predict negative (**NEG**)

• Our next goal is to estimate these parameters from the training data!

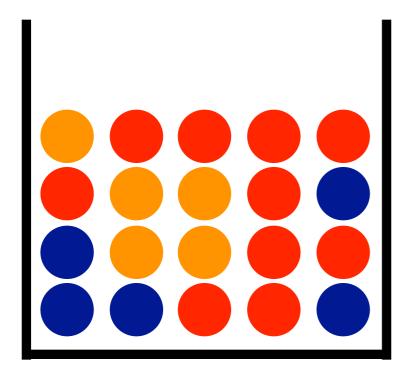




- Our next goal is to estimate these parameters from the training data!
- **P(NEG)** = % of training set documents that are **NEG**
- **P(POS)** = % of training set documents that are **POS**
- **P(D|NEG)** = ??
- **P(D|POS)** = ??

## Remember Conditional Probability?

P(RED) = 0.50P(BLUE) = 0.25P(ORANGE) = 0.25



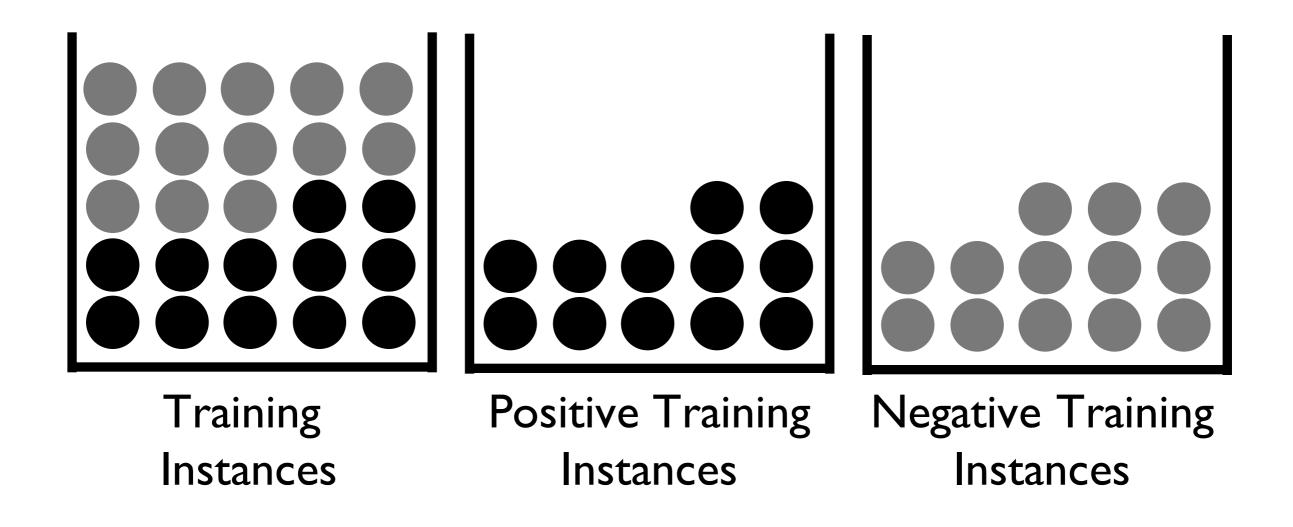
- $P(\bullet | A) = 0.25$
- P(-|A) = 0.50
- P( | A) = 0.25

P(RED) = 0.50P(BLUE) = 0.00P(ORANGE) = 0.50

•  $P(\bigcirc | B) = 0.00$ 

• 
$$P(-|B) = 0.50$$

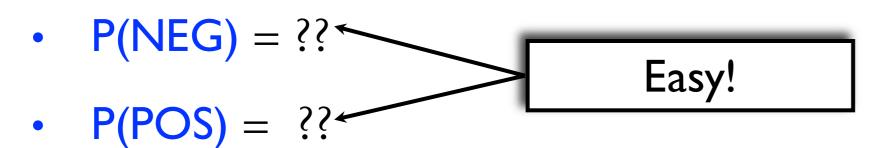
• P(-|B) = 0.50

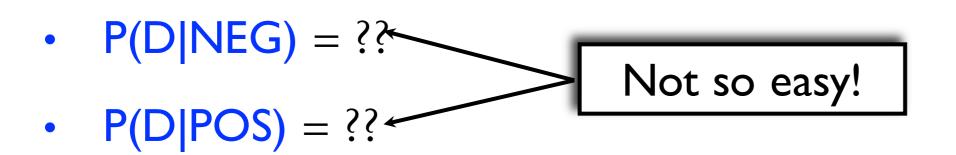


P(D|POS) = ?? P(D|NEG) = ??

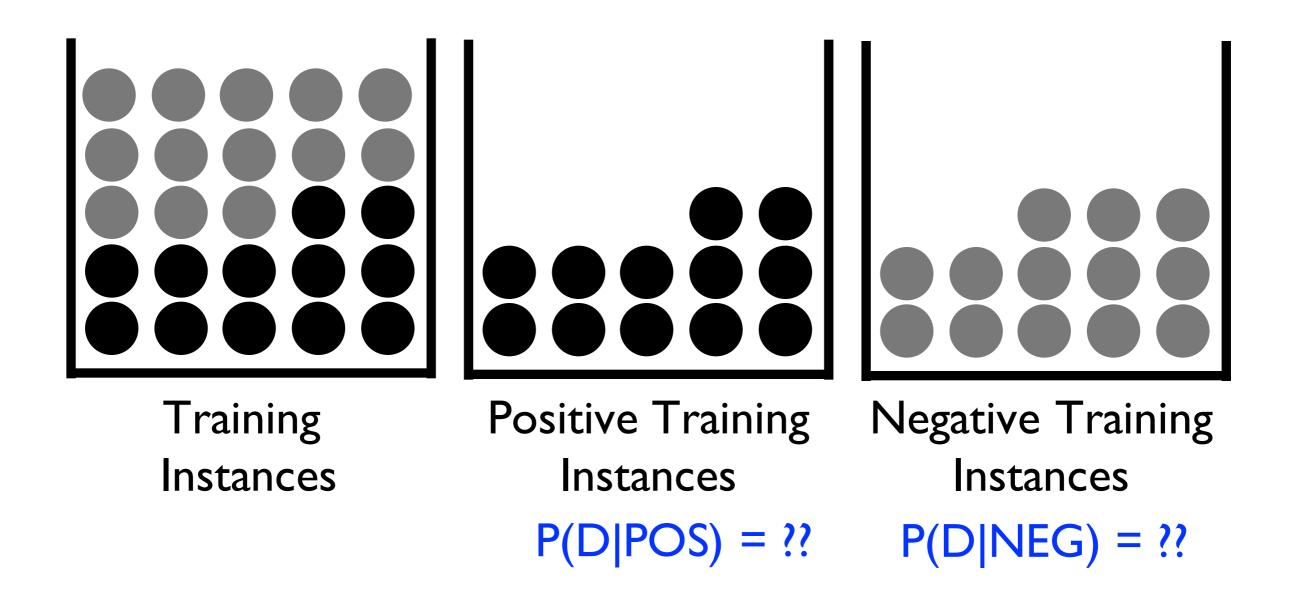
w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8		w_n	sentiment
1	0	I	0	I	0	0	I	•••	0	positive
0	I	0	I	I	0	I	I		0	positive
0	I	0	I	I	0	I	0		0	positive
0	0	I	0	I	I	0	I	••••	I	positive
	•	•	•	•	•	•	•	•••	•	
Ι	Ι	0	I	I	0	0	I		I	positive

• Our next goal is to estimate these parameters from the training data!

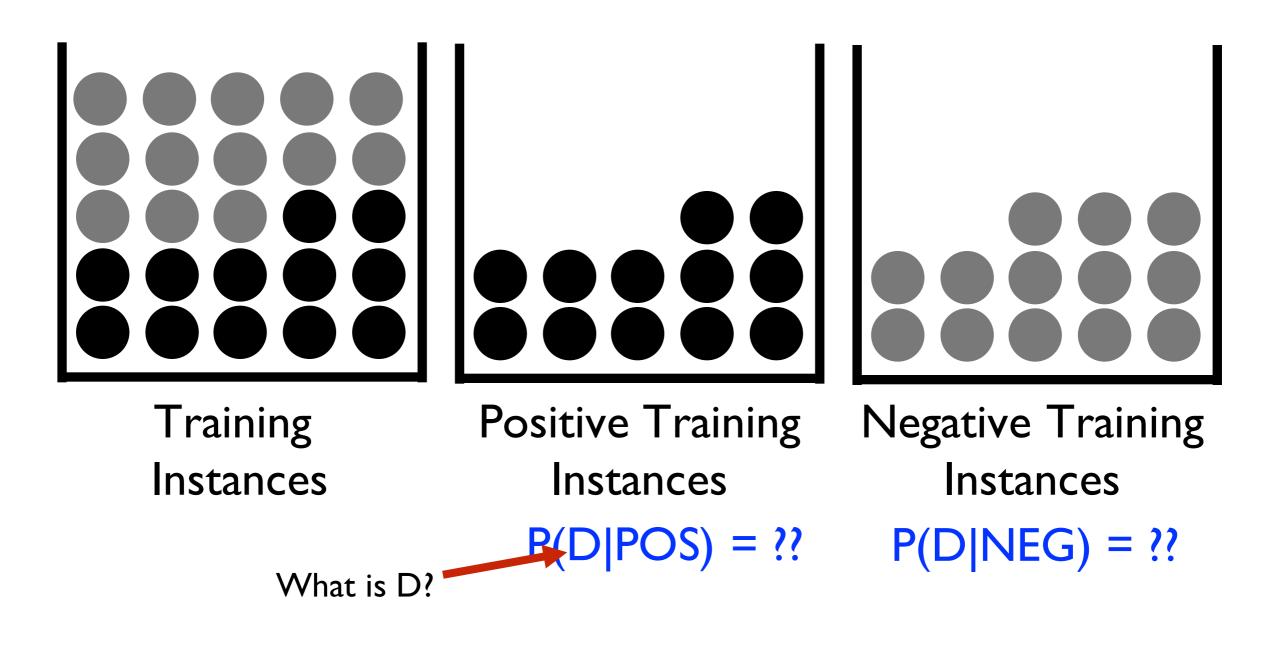




• We have a problem! What is it?



• We have a problem! What is it?



# What is the Document representation?

- Lets say that our feature space is limited by the following words: w\_1, w\_2, and w\_3.
- Total possible features are:
- w\_1, w\_2, w\_3
- w\_1 w\_2, w\_1 w\_3, w\_2 w\_3
- w\_1 w\_2 w\_3, w\_1 w\_2 w\_4
- Total = 8
- If say our feature space was: w\_1, w\_2, w\_3, and w\_4. Then total feature possible combinations are: ?

## Feature combinations

- Lets say that our feature space is limited by the following words: w\_1, w\_2, and w\_3.
- Total possible features are:
- w\_1, w\_2, w\_3
- w\_1 w\_2, w\_1 w\_3, w\_2 w\_3
- w\_1 w\_2 w\_3
- Total = 8 => 7 (above combinations) + 1 (no combination)
- If say our feature space was: w\_1, w\_2, w\_3, and w\_4. Then total feature possible combinations are: 2<sup>4</sup>

- We have a problem! What is it?
- Assuming n binary features, the number of possible combinations is 2<sup>n</sup>
- $2^{1000} = 1.071509e+301$
- And in order to estimate the probability of each combination, we would require multiple occurrences of each combination in the training data!
- We could never have enough training data to reliably estimate P(D|NEG) or P(D|POS)!

- Assumption: given a particular class value (i.e, POS or NEG), the value of a particular feature is independent of the value of other features
- In other words, the value of a particular feature is only dependent on the class value

w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8		w_n	sentiment
I	0	Ι	0	Ι	0	0	Ι	••••	0	positive
0	I	0	Ι	Ι	0	I	I		0	positive
0	Ι	0	Ι	Ι	0	Ι	0		0	positive
0	0	I	0	I	I	0	I		I	positive
•	•	•	•	•	•	••••			•	
Ι	Ι	0	Ι	Ι	0	0	Ι	•••	Ι	positive

## Example of document representation

- Assume the feature space to be the following words: hello, world, bad, movie.
- Review 1: "this is a bad movie!"
- Review 2: "hello world is a movie?"
- What is the bag-of-words document representation for review 1 and review 2?
- Review 1?
- Review 2?

## Example of document representation

- Assume the feature space to be the following words: hello, world, bad, movie.
- Review 1: "this is a bad movie!"
- Review 2: "hello world is a movie?"
- What is the bag-of-words document representation for review 1 and review 2?
- Review 1: 0011
- Review 2: 1101

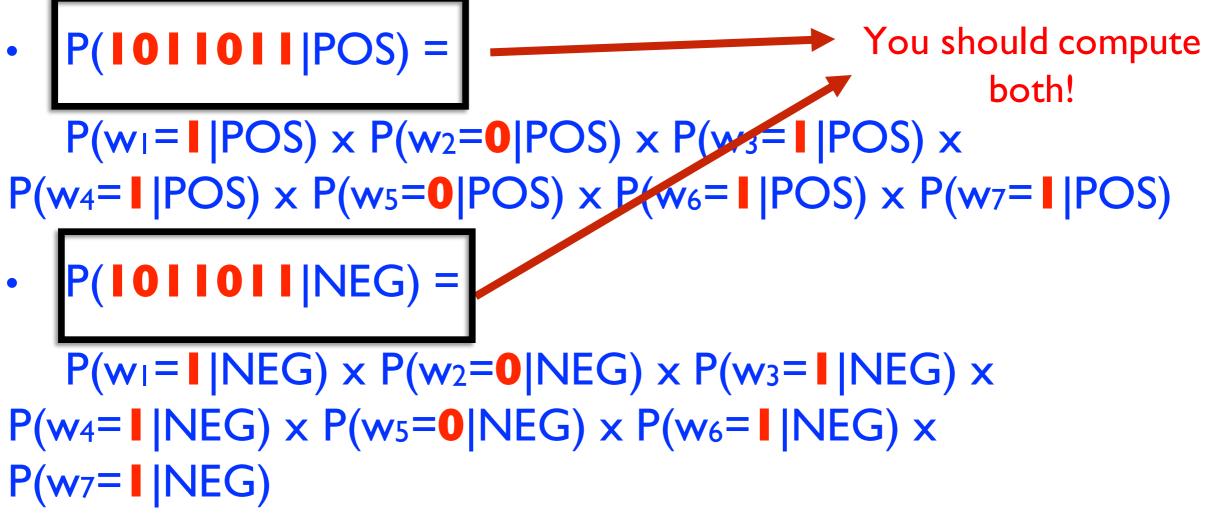
- Assumption: given a particular class value (i.e, POS or NEG), the value of a particular feature is independent of the value of other features
- Example: we have <u>seven</u> features and **D** = **IOIIOII**
- P(|0||0||POS) =

 $P(w_1=|POS) \times P(w_2=0|POS) \times P(w_3=|POS) \times P(w_4=|POS) \times P(w_5=0|POS) \times P(w_6=|POS) \times P(w_7=|POS)$ 

• P(|0||0||NEG) =

 $P(w_1=||NEG) \times P(w_2=0|NEG) \times P(w_3=||NEG) \times P(w_4=||NEG) \times P(w_5=0|NEG) \times P(w_6=||NEG) \times P(w_7=||NEG))$ 

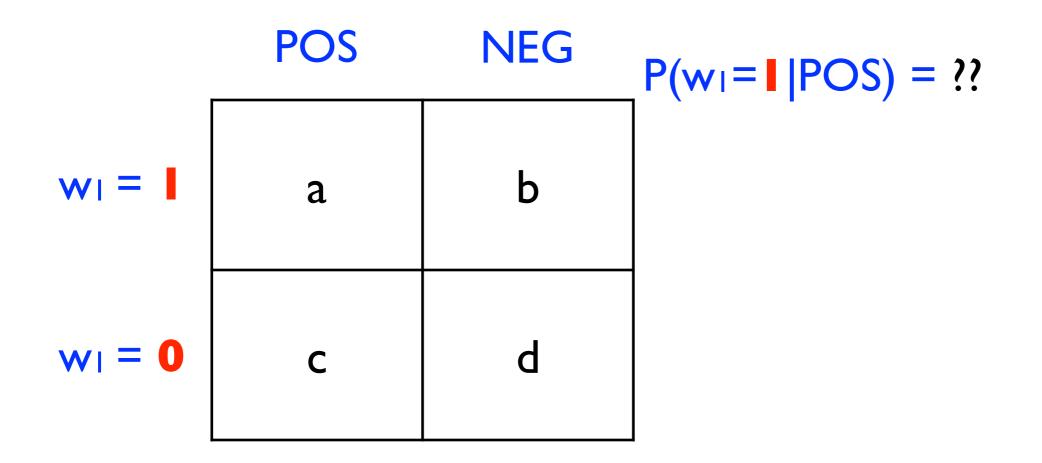
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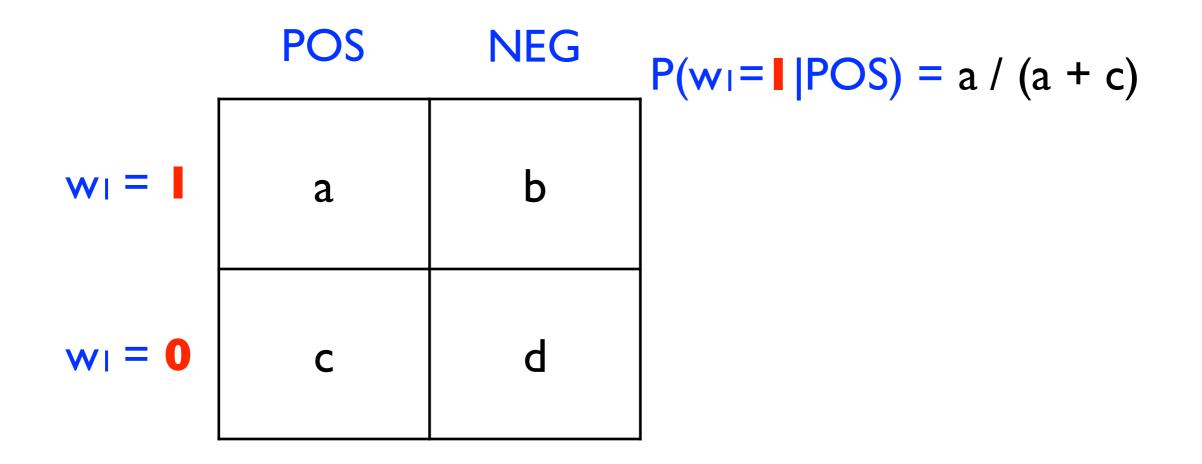
• Question: How do we estimate P(w = | POS) ?

w_I	w_2	w_3	w_4	w_5	w_6	w_7	w_8		w_n	sentiment
I	0	I	0	I	0	0	I	•••	0	positive
0	I	0	I	I	0	I	I	•••	0	negative
0	I	0	I	I	0	I	0	•••	0	negative
0	0	I	0	I	I	0	I		I	positive
	:	•	•	•	•	•			•	•
Ι	I	0	I	Ι	0	0	Ι	•••	Ι	negative

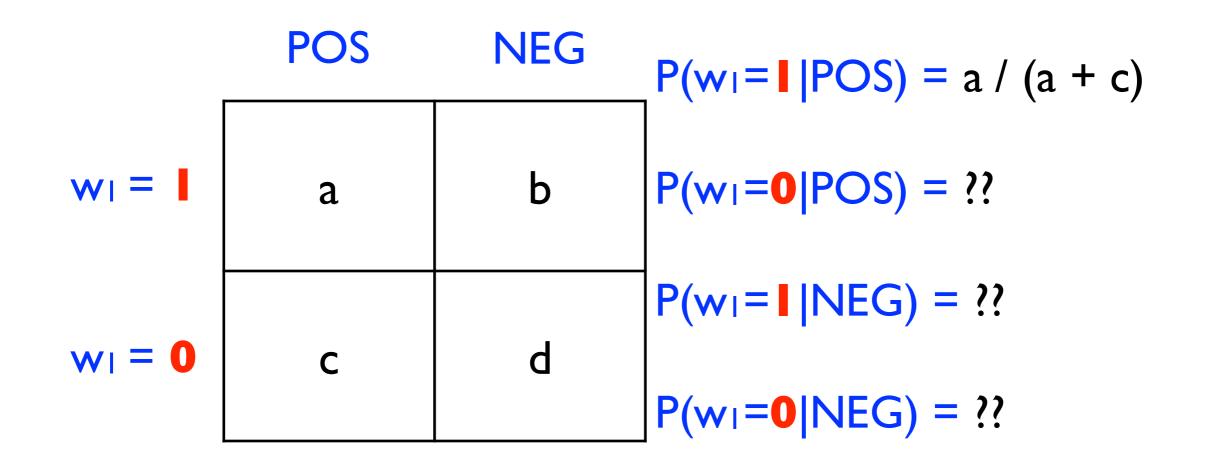
• Question: How do we estimate P(w1= POS) ?



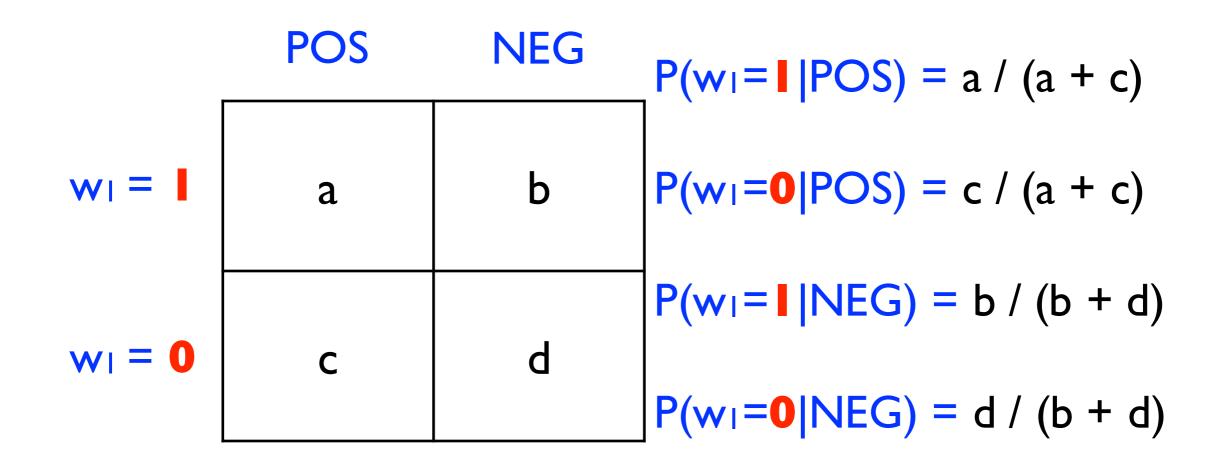
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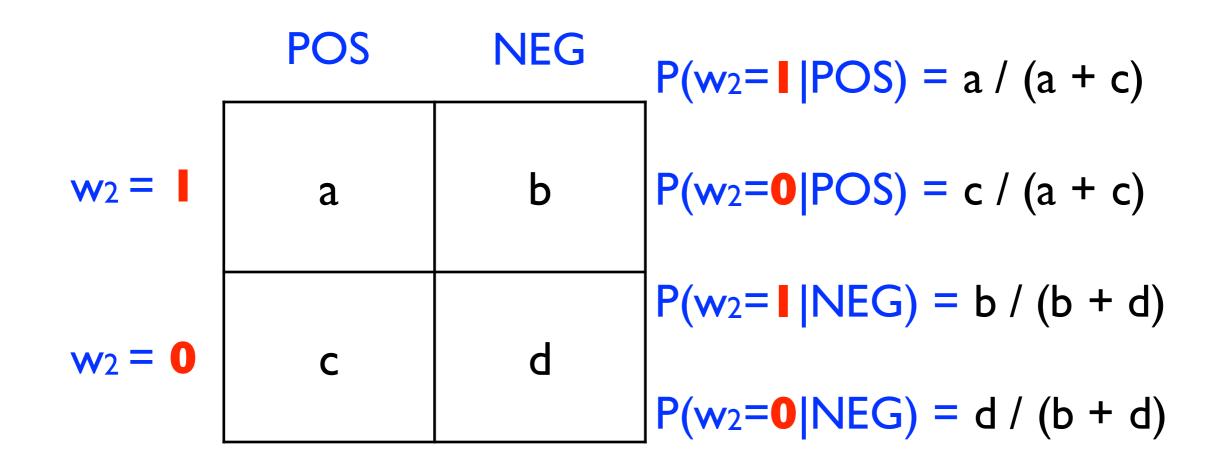
• Question: How do we estimate P(w1=1/0|POS/NEG)?



• Question: How do we estimate P(w1=1/0|POS/NEG)?



• Question: How do we estimate P(w<sub>2</sub>=1/0|POS/NEG)?



 The value of a, b, c, and d would be different for different features w1, w2, w3, w4, w5, ...., wn

• Given instance **D**, predict positive (**POS**) if:

#### $P(D|POS) \times P(POS) \ge P(D|NEG) \times P(NEG)$

• Given instance **D**, predict positive (**POS**) if:

$$P(POS) \times \prod_{i=1}^{n} P(w_i = D_i | POS) \ge P(NEG) \times \prod_{i=1}^{n} P(w_i = D_i | NEG)$$

Given instance D = [0][0][, predict positive (POS) if:
 P(w1=[POS) x P(w2=0|POS) x P(w3=1|POS) x P(w4=1|POS) x
 P(w5=0|POS) x P(w6=1|POS) x P(w7=1|POS) x P(POS)

#### $\geq$

 $P(w_1 = | | NEG) \times P(w_2 = 0 | NEG) \times P(w_3 = | | NEG) \times P(w_4 = | | NEG) \times P(w_5 = 0 | NEG) \times P(w_6 = | | NEG) \times P(w_7 = | | NEG) \times P(NEG) \times P(NEG)$ 

• We still have a problem! What is it?

• Given instance D = |0||0||, predict positive (POS) if:  $P(w_1=|POS) \times P(w_2=0|POS) \times P(w_3=|POS) \times P(w_4=|POS) \times P(w_5=0|POS) \times P(w_6=|POS) \times P(w_7=|POS) \times P(POS)$ 

 $P(w_1 = | | NEG) \times P(w_2 = 0 | NEG) \times P(w_3 = | | NEG) \times P(w_4 = | | NEG) \times P(w_5 = 0 | NEG) \times P(w_6 = | | NEG) \times P(w_7 = | | NEG) \times P(NEG) \times P(NEG)$ 

Otherwise, predict negative (NEG)

What if this never happens in the training data?

## **Smoothing Probability Estimates**

- When estimating probabilities, we tend to ...
  - Over-estimate the probability of observed outcomes
  - Under-estimate the probability of unobserved outcomes
- The goal of smoothing is to ...
  - Decrease the probability of observed outcomes
  - Increase the probability of unobserved outcomes
- It's usually a good idea
- You probably already know this concept!

## **Smoothing Probability Estimates**

- YOU: Are there mountain lions around here?
- YOUR FRIEND: Nope.
- YOU: How can you be so sure?
- YOUR FRIEND: Because I've been hiking here five times before and have never seen one.
- YOU: ????

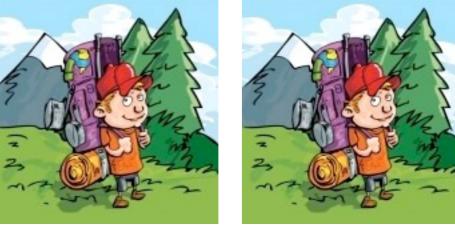




## **Smoothing Probability Estimates**

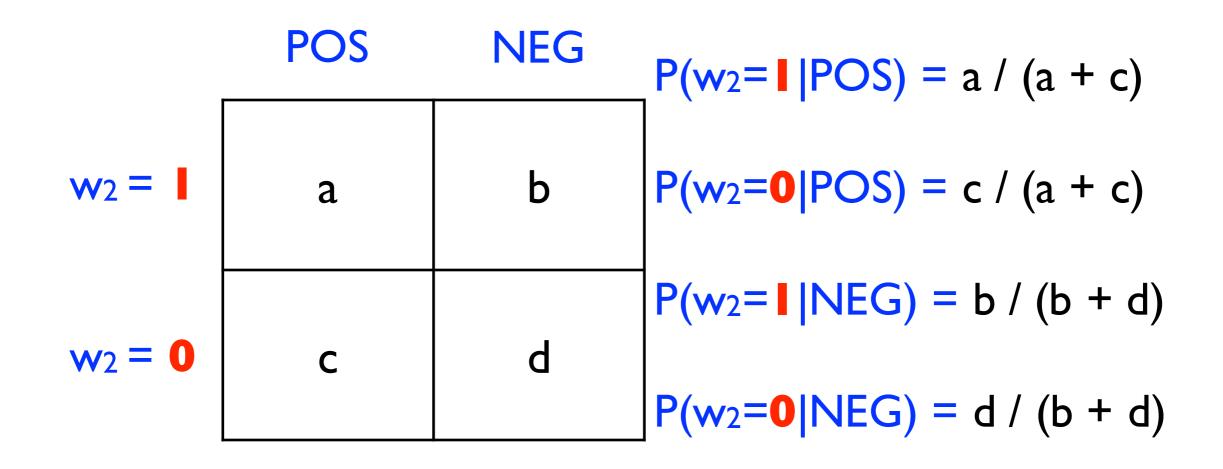
- YOU: Are there mountain lions around here?
- YOUR FRIEND: Nope.
- YOU: How can you be so sure?
- YOUR FRIEND: Because I've been hiking here five times before and have never seen one.
- MOUNTAIN LION: You should have learned about smoothing by taking INLS 613. Yum!





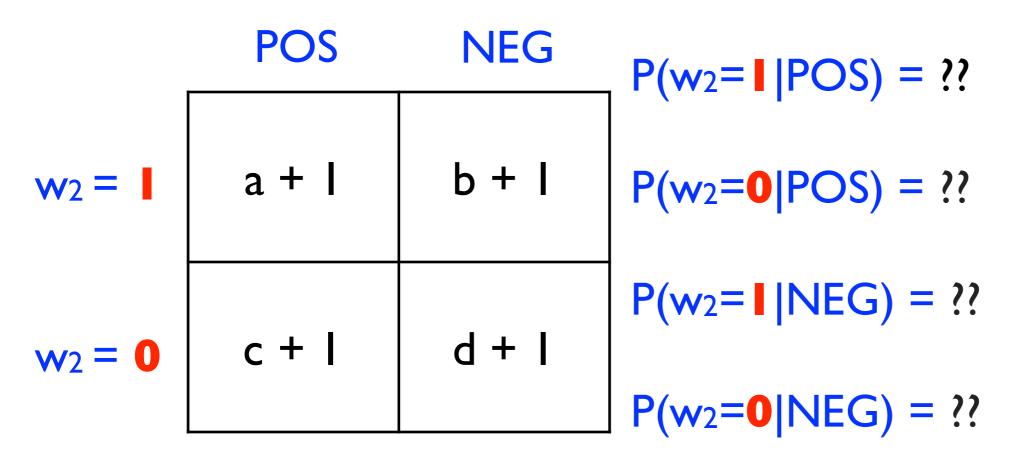
## Add-One Smoothing

• Question: How do we estimate P(w<sub>2</sub>=1/0|POS/NEG)?



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## Add-One Smoothing

• Question: How do we estimate P(w<sub>2</sub>=1/0|POS/NEG)?

	POS	NEG	$- P(w_2 =   P \cap S ) = (a + 1) / (a + c + 2)$
w <sub>2</sub> =	a + 1	b + 1	$P(w_2=1 POS) = (a + 1) / (a + c + 2)$ $P(w_2=0 POS) = (c + 1) / (a + c + 2)$
w <sub>2</sub> = <b>0</b>	c +	d + 1	$P(w_2=  NEG) = (b + 1) / (b + d + 2)$
			$P(w_2=0 NEG) = (d + I) / (b + d + 2)$

• Given instance **D**, predict positive (**POS**) if:

$$P(POS) \times \prod_{i=1}^{n} P(w_i = D_i | POS) \ge P(NEG) \times \prod_{i=1}^{n} P(w_i = D_i | NEG)$$

## Naive Bayes Classification

- Naive Bayes Classifiers are simple, effective, robust, and very popular
- Assumes that feature values are conditionally independent given the target class value
- This assumption does not hold in natural language
- Even so, NB classifiers are very powerful
- Smoothing is necessary in order to avoid zero probabilities